# **Netter**Vibration



**Assembly and Operating Instructions** 

for Vibration Monitoring System Series *VibroMonitor*  May 2019 No. 1683E Page 1/16

These assembly and operating instructions apply to:

Control Unit NVM C1W
Control Unit NVM C4W
Control Unit NVM C4
Sensor NVM S10



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# Scope of supply



Check the packing for possible shipping damage.

If the packing is damaged, check the contents for completeness and possible damage. In case of damage inform the transport agent. IMPORTANT Compare the scope of supply with the delivery note.

#### 1 General Notes

Netter vibration monitoring systems series *VibroMonitor* comply with the Electromagnetic Compatibility Directive 2014/30/EU and the Low Voltage Directive 2014/35/EU. In particular, the standards DIN EN 61010-1 and DIN EN 61326-1 have been observed.

Vibration monitoring systems are used for permanent monitoring applications as they are required for impactors, vibrators and vibrating systems.

## **Special features:**

- Permanent monitoring of vibration systems
- Radio suppression
- Operation mode: electronic
- Control unit mounted on M36-DIN rail

#### Important note:



Before use of the Netter vibration monitoring systems series *Vibro*Monitor read these assembly and operating instructions carefully and keep them stored close to the vibrators afterwards.

This documentation is copyrighted. All rights, e.g. for translation into other languages, reprinting and copying of these operating instructions or parts hereof remain strictly reserved.

In these operating instructions the following information and danger symbols are used.

A	DANGER	points out a possible danger which will result in death or serious injury if the respective instruction is not complied with.		
A	WARNUNG	points out a possible danger which might lead to personal injury or equipment damage if the respective instruction is not complied with.		
	DISCONNECT UNIT FROM MAINS SUPPLY	points out a possible danger which might lead to personal injury if the respective instruction is not complied with.		
	IMPORTANT	Note containing especially useful information and tips.		
	ENVIRONMENTALLY FRIENDLY WASTE	points out the obligation to dispose of waste in an environmentally friendly way.		

**DISPOSAL** 

# 2 Safety

#### Intended use:

The vibration monitoring systems are designed for installation in machines. These devices use vibrations for sieving, loosening, conveying, compacting and separating bulk material.

Any other use is considered improper use.

## **Qualification of the personnel:**

Assembly, commissioning, maintenance and repair of the vibration monitoring systems must be performed only by authorized qualified personnel.

Any handling of the vibration monitoring systems lies within the responsibility of the user.

Accessories which ensure the correct operation and safety must provide a protection type required for the specific use.



Live parts can cause severe or fatal injuries.

The vibration monitoring systems are built in accordance with the latest EC directives.



The assembly, installation, commissioning and maintenance must be performed only by authorized personnel.

The installation and operation of the vibration monitoring system is to be carried out in accordance with the requirements of the local electrical engineering associations (e.g. VDE) and the known accident prevention rules.



Netter GmbH will not be liable for any damage or injury if the product has been technically modified or if the instructions of this operating manual have not been observed.



When working on the vibrators, these must be isolated from the mains supply. To do so, please proceed as follows:

- 1. Switch off the vibrator.
- 2. Secure against re-activation.
- 3. Establish that there is no voltage.
- 4. Earth and short-circuit.
- 5. Cover neighbouring live parts or fence them off.

# 3 Technical Data



Operating voltage:
Ambient temperature:

24V DC (+20%/-10%), <5% residiual ripple
Control unit C1W 0°C to 40°C
Control unit C4W 0°C to 40°C
Control unit C4 -20°C to 40°C
Sensor S10 -20°C to 40°C
The ambient temperature range must not be exceeded of fallen short of.

<b>Vibro</b> Monitor	Control unit Type NVM C1W	Control unit Type NVM C4W    14   15   16   17   18   19   20   21   22   23   24   25     14   15   16   17   18   19   20   21   22   23   24   25     15   15   25   33   34     16   17   18   19   20   21   22   23   24   25     17   18   19   20   21   22   23   24   25     18   18   20   21   22   23   24   25     19   19   10   10   10     10   10   10   10     11   12   13     12   13   14   15   16   7   8   9   10   11   12   13     13   14   15   16   7   8   9   10   11   12   13     19   19   19   10   11   12   13     19   19   10   11   12   13     10   10   10   10   10   10   10     10   10	
Sensor inputs	1 × unpolarized	4 × unpolarized	
Relay outputs	1 × switching output  4 × switching output  potential-free change-over, max. 30 V DC, max. 2 A  If the acceleration value is <i>greater</i> than the set threshold, the normally open contact <i>closes</i> (the NC contact opens). If the acceleration value is <i>lower</i> than the set threshold, the normally open contact <i>opens</i> (the NC contact		
Digital outputs	closes).  1 × fault output,  NPN, not potential free, max. 1 A  If there is a sensor connection error, an external load (at		
+24 V DC) is pulled to 0 V 1 × operating voltage 1 × sensor status		8 × sensor status	
Faults		break- or short-circuit) 2 × SET inputs  Externally via a switch to	
Setting		0 V Internally via a button on the board	
Installation	M36-DIN standa <mark>r</mark> d rail (EN50022)		
Dimensions H×W×D	70 × 35 × 90 mm	$70 \times 70 \times 90 \text{ mm}$	

<b>Vibro</b> Monitor	Control unit Typ NVM C4  14 18 16 17 18 19 20 21 22 23 24 25     SS 52 53 54
Sensor inputs Digital outputs	4 × unpolarized 4 × NPN, max. 8 mA
Digital outputs	<ul> <li>If the acceleration value is greater than the set switching value, an external load (to +24 V DC) is pulled to 0 V.</li> <li>If the acceleration value is less than the set switching value, an external load remains on its potential (+24 V DC).</li> </ul>
Status LEDs	1 × operating voltage control, 4 × sensor status
Fault	4 x visual indicator display
Mounting	M36-DIN standard rail (EN50022)
Dimensions HxWxD	70 × 70 × 90 mm

<b>Vibro</b> Monitor	Sensor NVM S10		
Туре	capacitive, monocrystalline (MEMS), integrated amplifier		
Connection	4-pin socket for round connectors M12 x 1 (preferably with cap nut and interlock)		
Material	cylindrical sensor made of stainless steel		
Shock acceleration	max. 100 g (peak)		
Adjustable switching	le switching 0-7 g (RMS), 0-10 g (peak)		
threshold	Standard setting: 3,5 g (RMS), 5,0 g (peak)		
Length of cable	between sensor and control unit: max. 250 m		
Dimensions h x w x d	Ø 12 x 40, thread (plug) M12 x 1		

The connection diagram is shown on the type plate.

# 4 Design and Functioning

The **Vibro**Monitor vibration monitoring system is used for the constant monitoring of vibration units. It consists of up to four acceleration sensors and a control unit, which provides both the power supply for the sensors and signal analysis.

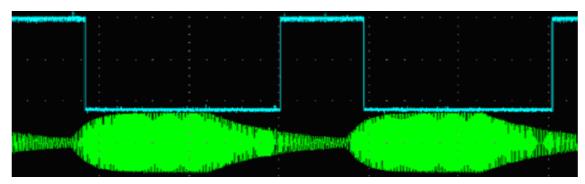
In combination with a controller the signals can be directly used for additional operations.

The system distinguishes two conditions for each connected sensor.

- 1. Vibration active
- 2. No vibration

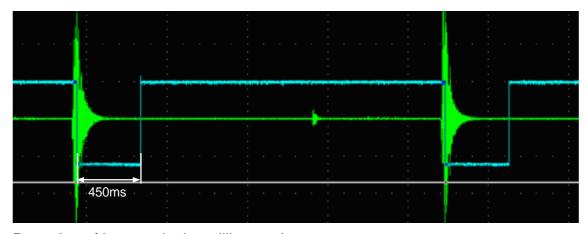
If the acceleration at a sensor is higher than the set switching threshold (standard 5 g peak, 3,5 g RMS), the "Vibration active". system reports Accelerations the switching below threshold lead to the signal vibration".

To ensure that also short impacts, e.g. of impactors, are reliably detected, the "Vibration active" signal has a delay time of 450 ms.



Monitoring of a vibrator with a frequency of 50 Hz.

The digital output of the VibroMonitor (blue) shows the accelerations (green) when exceeding the switching threshold.



Detection of impacts in the millisecond range.

The digital output of the *VibroMonitor* (blue) holds its status for at least 450 ms and therefore reliably records even short impacts (green acceleration signal).

# 5 Transport and Storage



Check the packaging for possible shipping damage.

If damage to the packaging is found, check the content for completeness and possible damage. In case of damage, inform the forwarding agent.

The units are packed ready for installation. When transporting the vibration monitoring system, make sure that the unit is not subject to extreme shocks or vibrations.

The unit should be stored in a clean, dry environment.

If the vibration monitoring system needs to be in storage for a longer period of time, the temperature in the store must not lie below 0 °C or above 40 °C and the relative air humidity must not exceed 60%.

# 6 Assembly

The control unit is to be mounted on a M36-DIN-standard rail.

For protection against dust and water jets (protection type IP 65) it has to be installed in a switch box or switch cabinet.

The sensors are mounted directly on the vibrating part with use of a plastic clamp holder or a rubberized clamp.

Bear in mind that for linear vibrations the longitudinal axis of the sensor must be parallel to the direction of vibration.



During installation, the safety regulations in chapter 2 and the accident prevention rules must be strictly observed!

Installation of the system must be performed in compliance with the local, applicable regulations (e.g. VDE regulations).

Use a suitable supply cable for the installation. Connect cables and protective conductors correctly.



The electric cables have to be installed carefully and it has to be ensured that the cables are not worn through by vibrating parts.

The proper condition of the electric cables and plugs has to be checked at regular intervals (as a rule every six months). Discovered faults have to be immediately eliminated.

Protect the cable against high temperatures, lubricants and sharp edges.

#### 6.1 Connection of control unit NVM C1W

The Control unit needs an operating voltage of 24 V DC.

Connection: C1W

Clamp 5: +24 V DC, clamp 6: 0 V.

The acceleration sensor is connected to the input clamps 2 + and 1 -.

Attention: Make sure polarity is correct.

The sensor status can be captured using a relay output on **clamps 7 to 9**. The external voltage source is connected to **clamp 9**. If the acceleration at the sensor exceeds the switching threshold, the relay contact connects **clamps 7 and 9** or disconnects **clamps 8 and 9**. Once the

acceleration drops below the switching threshold, at the earliest, however, after **450 ms**, the relay contact returns to its initial position, disconnecting **clamps 7** and 9 and reconnecting **clamps 8 and 9**. The maximum switching voltage must not exceed **30 V DC**, the maximum permitted switching current is **2.0 A**. It is possible to use the **NPN output** on **clamp 10** to query externally whether there is a fault. The fault outputs on several NVM C1 control units can be monitored simultaneously by parallel connection.



Clamp	Configuration
1	Canaarianut
2	Sensor input
3	-
4	Power LED
5	+ 24 V
6	0 V
7	Relay output NO contact
8	Relay output NC contact
9	Relay output lead
10	NPN fault output
11	Status LED
12	-

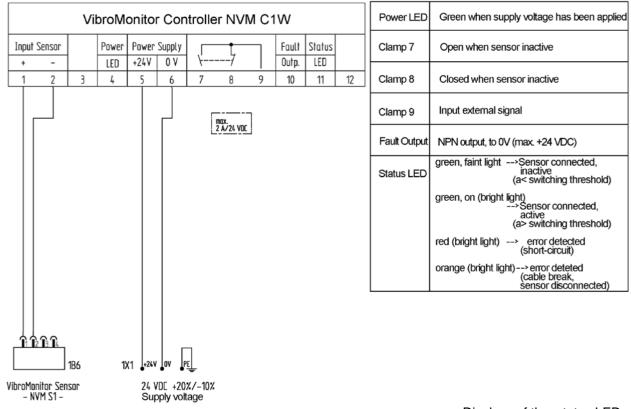
Clamp assignment NVM C1W

### 6.2 LED status display control unit NVM C1W

The power LED (clamp 4) indicates whether the operating voltage is applied and the fuse of the voltage input is intact.

If the operating voltage is applied to the control unit, the status LED (clamp 11) lights up for about 3 seconds provided that the sensor is properly connected and working. Then, the system is ready for operation. During operation, the status LED will show a faint light, if the sensor is connected and ready to operate and the measured acceleration is below the set switching threshold.

the acceleration at the exceeds the switching threshold, the status LED will change to bright light. If no sensor is connected, the sensor is not correctly connected, or there is a cable break, the status LED lights up orange. If there is a short circuit in the sensor cable, the status LED lights up red. In case of short circuits lasting more than 500 ms. the unit must disconnected from the supply voltage to reset it.



Displays of the status LED

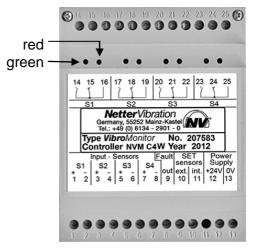
#### 6.3 Connection of control unit NVM C4W

The control unit requires an operating voltage of **24 V DC**.

Connection:

Clamp 12: +24 V DC, clamp 13: 0 V. Up to four sensors can be connected to the input clamps 1 to 8 (S1 to S4), whereby attention needs to be paid to the polarity.

Via the relay outputs at the **clamps 14 to 25** (S1 to S4) the status of the sensors can be captured e.g. for the digital inputs of a PLC.



Clamp	Configuration	Clamp	Configuration
1	Concor input 1	14	NO
2	Sensor input 1	15	NC
3	Concor input 2	16	COM
4	Sensor input 2	17	NO
5	Concor input 2	18	NC
6	Sensor input 3	19	COM
7	Sensor input 4	20	NO
8	Sensor input 4	21	NC
9	Fault out	22	COM
10	SET sensors ext.	23	NO
11	SET sensors int.	24	NC
12	+ 24 V	25	COM
13	0 V		

Clamp configuration NVM C4W

Clamp configuration NVM C4W

· .				
red	off	_	concer not tought	
green	off	=	sensor not taught	
red	on	_	broken cable	
green	off	=	brokeri cable	
red	on	_	short circuit	
green	on	_	SHOIL CITCUIL	
red	off	_	concer recognised	
green	on (dimmed)	=	sensor recognised	
red	off		sensor has reached switching threshold	
green	on (bright)	=	Sensor has reached switching threshold	

# 6.4 LED status display control unit NVM C4W

If operating voltage is applied to the control unit, the status LEDs assigned to the sensors light up if the respective sensors are properly connected and working. Then, the system is ready for operation. During operation, the respective status LED shows a weak light, if the associated sensor is connected and ready to operate, and the

measured acceleration is below the switching threshold. If the acceleration at one of the sensors exceeds the switching threshold, the associated status LED shows a bright light and the respective output switches. The fault LED lights up either in case of cable break, not connected sensor or if there is a short-circuit in the sensor input.

# 6.5 Adjusting the number of sensors at the control unit NVM C4W

If not all sensor connections of the control unit are required, not used inputs and outputs can be switched off.

After applying the operating voltage the connected sensors will be detected by the status LEDs. If e.g. only 2 sensors are connected to S1 and S2, the green status LEDs at S1 and S2 and the red error LEDs at S3 and S4 light up and the output fault shows an error. This can indicate that either no sensors are connected to S3 and S4 or that there is a short-circuit or cable break on the respective sensors. If the sensor inputs S3 and S4 (or any other combination)

are not required, the control unit can be adjusted to the connected sensors. This can be done via PIN 10 using an external button with a reference potential of 0V or via PIN 11 using a button in the housing. To teach the control unit, the external or internal switches are activated at least 3 seconds. After this the control unit is adjusted to the connected sensors which can be seen by the extinguished error LEDs. This condition is maintained even in case of voltage failure until the push-button is activated for at least 0,5 s.

#### 6.6 Connection of control unit NVM C4

The control unit requires an operating voltage of **24 V DC**.

Connection:

Clamp 12: +24 V DC, clamp 13: 0 V. Up to four sensors can be connected to the input clamps 1 to 8 (S1 to S4), whereby attention needs to be paid to the polarity.

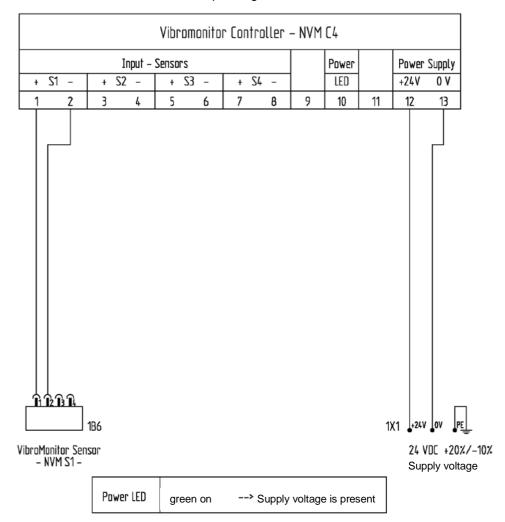
Via the relay outputs at the **clamps 14 to 25** (S1 to S4) the status of the sensors can be captured e.g. for the digital inputs of PLC.

By means of active PNP inputs, e. g. digital inputs of a PLC, the status of the sensors at the output clamps 16 to 19 (S1 to S4) can be captured.

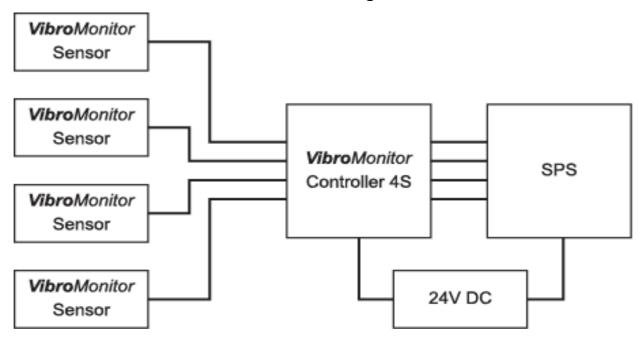


Clamp	Configuration	Clamp	Configuration
1	Concer input	14	-
2	Sensor input1	15	-
3	Sensor input 2	16	NPN output 1
4	Sensor input 2	17	NPN output 2
5	Concor input 2	18	NPN output 3
6	Sensor input 3	19	NPN output 4
7	Sensor input 4	20	Status LED 1
8	Sensor input 4	21	Status LED 2
9	-	22	Status LED 3
10	Power LED	23	Status LED 4
11	-	24	-
12	+ 24 V	25	-
13	0 V		

Clamp configuration NVM C4



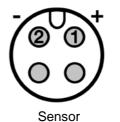
# **Connection Diagram**

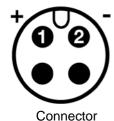


## 6.7 Connection of sensor

The sensor has a socket for a 4-pin plug connector with nut M12 x 1 (preferably with integrated screw locking).

The length of the sensor cable must not exceed 250 m.

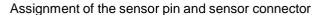




Pins 1 and 2 need to be connected to one of the two-pole sensor inputs on the control unit.

Pin 1 = +

Pin 2 = -





# 7 Spare Parts

When ordering spare parts, you should always provide the following details:

- 1. Type of unit
- 2. Description and part number
- 3. Required quantity

## 8 Annex

## 8.1 Accessories

Connecting components	
Sensor connecting cable 5 m	With angled socket
	M12 $\times$ 1 and free cable end,
	Material: PUR
	Part No.: 65000254
Sensor connecting cable 10 m	With angled socket
	$M12 \times 1$ and free cable end,
	Material: PUR
	Part No.: 65000307
Sensor connector M12 x 1 angled	With angled socket M12×1 and
	plastic interlock
	Part No.: 61703220
Sensor connector M12 x 1 straight	With straight cable connector M12 x 1
	and plastic interlock
	Part No.: 61703221

Clamps	
Sensor clamp	Plastic design,
	Material: Polyamide,
	Color: black
	Fixing: for 2 × M5
	Part No.: 61703219
Sensor clamp	Design: rubber-coated stainless steel
	pipe clamp
	Mounting hole Ø 8,4 mm
	Part No.: 61703218

## 8.2 Disposal

Depending on the material, the parts must be disposed of in an expert way.



All units can be disposed of through Netter GmbH. The valid disposal prices are available on request.

## 8.3 Enclosures

**Enclosure(s):** 

**Declaration of Conformity** 



Further information available on request: **Leaflet No. 38 and others**